



Modeling and Simulation of the Thermo-Acousto-Elastic Waves in Solids of Complex Rheology

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Two-components material point



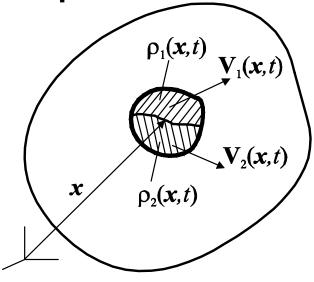


Fig.1

$$\rho_m(\mathbf{x}, t) = \rho_1(\mathbf{x}, t) + \rho_2(\mathbf{x}, t)$$

$$\rho_m(\mathbf{x}, t) \mathbf{V}_m(\mathbf{x}, t) = \rho_1(\mathbf{x}, t) \mathbf{V}_1(\mathbf{x}, t) + \rho_2(\mathbf{x}, t) \mathbf{V}_2(\mathbf{x}, t)$$

Intercomponental interaction $-{f R}$, heat exchange - $\kappa(T_1-T_2)$





Mass conservation law

For medium

$$\frac{\partial \rho_m}{\partial t} + \nabla \cdot (\rho_m \mathbf{V}_m) = 0$$

For each component

$$\frac{\partial \rho_1}{\partial t} + \nabla \cdot (\rho_1 \mathbf{V}_1) = \chi$$
$$\frac{\partial \rho_2}{\partial t} + \nabla \cdot (\rho_2 \mathbf{V}_2) = -\chi$$

 χ - the source of mass





Momentum conservation law

For medium

$$\nabla \cdot \boldsymbol{\tau}_m + \rho_m \mathbf{F}_m = \rho_1 \frac{d\mathbf{V}_1}{dt} + \rho_2 \frac{d\mathbf{V}_2}{dt} + \chi \left(\mathbf{V}_1 - \mathbf{V}_2 \right)$$

For each component

$$\nabla \cdot \boldsymbol{\tau}_1 + \rho_1 \mathbf{F}_1 + \mathbf{Q} = \rho_1 \frac{\mathsf{d} \mathbf{V}_1}{\mathsf{d} t} + \chi \mathbf{V}_1$$
$$\nabla \cdot \boldsymbol{\tau}_2 + \rho_2 \mathbf{F}_2 - \mathbf{Q} = \rho_2 \frac{\mathsf{d} \mathbf{V}_2}{\mathsf{d} t} - \chi \mathbf{V}_2$$

Total stress and external forces

$$\tau_m = \tau_1 + \tau_2, \quad \tau_1 = \tau_1(\varepsilon_1, ...), \quad \tau_2 = \tau_2(\varepsilon_2, ...)$$

$$\rho_m \, \mathbf{F}_m = \rho_1 \, \mathbf{F}_1 + \rho_2 \, \mathbf{F}_2$$





The equations of the balance of energies

$$\rho_{1} \left(\frac{d_{1}U_{1}}{dt} + \mathbf{V}_{1} \cdot \nabla U_{1} \right) = \tau_{1} \cdot \cdot \cdot \nabla \mathbf{V}_{1} + \frac{1}{2} \mathbf{Q} \cdot (\mathbf{V}_{2} - \mathbf{V}_{1}) - \nabla \cdot \mathbf{h}_{1} + \rho_{1}q_{1} + \chi_{m1} \left(\frac{1}{2} \mathbf{V}_{1} \cdot \mathbf{V}_{1} - U_{1} \right) - Q$$

$$\rho_{2} \left(\frac{d_{2}U_{2}}{dt} + \mathbf{V}_{2} \cdot \nabla U_{2} \right) = \tau_{2} \cdot \cdot \cdot \nabla \mathbf{V}_{2} + \frac{1}{2} \mathbf{Q} \cdot (\mathbf{V}_{2} - \mathbf{V}_{1}) - \nabla \cdot \mathbf{h}_{2} + \rho_{2}q_{2} + \chi_{m2} \left(\frac{1}{2} \mathbf{V}_{2} \cdot \mathbf{V}_{2} - U_{2} \right) + Q$$





The second law of thermodynamics

$$\frac{d}{dt} \int_{(V)} \rho_1 S_1 dV \ge \int_{(V)} \left[\frac{\rho_1 q_1}{\theta_1} + \frac{Q}{\theta_2} \right] dV - \int_{(S)} \mathbf{n} \cdot \left[\frac{\mathbf{h}_1}{\theta_1} - \rho_1 \mathbf{V}_1 S_1 \right] dS$$

$$\frac{d}{dt} \int_{(V)} \rho_2 S_2 dV \ge \int_{(V)} \left[\frac{\rho_2 q_2}{\theta_2} - \frac{Q}{\theta_1} \right] dV - \int_{(V)} \mathbf{n} \cdot \left[\frac{\mathbf{h}_2}{\theta_2} - \rho_2 \mathbf{V}_2 S_2 \right] dS$$





Models of materials

The particles balance equations

$$\begin{cases} \frac{\partial \tilde{n}_1}{\partial t} + \nabla \cdot (n_1 \, \mathbf{v}_1) = J_{12} \\ \frac{\partial \tilde{n}_2}{\partial t} + \nabla \cdot (n_2 \, \mathbf{v}_2) = J_{21} \end{cases}$$

$$\rho_1 = m_1 n_1, \quad \rho_2 = m_2 n_2$$

$$\rho_m = \rho_1 + \rho_2,$$

$$\rho_m \mathbf{v}_m = \rho_1 \mathbf{v}_1 + \rho_2 \mathbf{v}_2$$

$$\begin{cases} \frac{\partial \tilde{n}_{1}}{\partial t} + \nabla \cdot (n_{1} \mathbf{v}_{1}) = J_{12} & \rho_{1} = m_{1}n_{1}, \ \rho_{2} = m_{2}n_{2} \\ \frac{\partial \tilde{n}_{2}}{\partial t} + \nabla \cdot (n_{2} \mathbf{v}_{2}) = J_{21} & \rho_{m} = \rho_{1} + \rho_{2}, \\ \rho_{m} \mathbf{v}_{m} = \rho_{1} \mathbf{v}_{1} + \rho_{2} \mathbf{v}_{2} \end{cases} \begin{cases} \frac{\partial \rho_{1}}{\partial t} + \nabla \cdot (\rho_{1} \mathbf{v}_{1}) = \chi_{12} \\ \frac{\partial \rho_{2}}{\partial t} + \nabla \cdot (\rho_{2} \mathbf{v}_{2}) = \chi_{21} \end{cases}$$

The Kelvin model





Influence of source terms on stress - strain state by chemical reaction

Let the medium B with the density ho_{B_0} after a chemical reaction go into the medium A with the density ho_{A0} .

Suppose that at the first approximation the chemical reactions do not depend on the stress state. That's why we can assume that sources χ_{BA} and χ_{AB} in the balance equations are known.

$$\begin{cases} \frac{\partial \rho_B}{\partial t} + \nabla \Box (\rho_B \mathbf{v}_B) = -\dot{\chi}_{BA} \rho_{B_0} \\ \frac{\partial \rho_A}{\partial t} + \nabla \Box (\rho_A \mathbf{v}_A) = \dot{\chi}_{AB} \rho_{A_0} \end{cases}$$

$$\chi_{BA}\rho_{B0}=\chi_{AB}\rho_{A0}$$





For the one-dimensional case

$$\begin{cases} \frac{\partial \rho_B}{\partial t} + \frac{\partial}{\partial x} (\rho_B \mathbf{v}_B) = -\dot{\chi}_{BA} \rho_{B_0} \\ \frac{\partial \rho_A}{\partial t} + \frac{\partial}{\partial x} (\rho_A \mathbf{v}_A) = \dot{\chi}_{AB} \rho_{A_0} \end{cases}$$

Suppose that in both media the spherical part of Cauchy stress tensor

depends on
$$\xi_{\scriptscriptstyle AB} = 1 - \frac{\rho_{\scriptscriptstyle AB}}{\rho_{\scriptscriptstyle AB}^{(0)}}$$

$$\begin{cases} \sigma_B = \sigma_B \left(1 - \frac{\rho_B}{\rho_B^{(0)}} \right) \\ \sigma_A = \sigma_A \left(1 - \frac{\rho_A}{\rho_A^{(0)}} \right) \end{cases}$$





Density $ho_{\it B}$ we shall seek in the form

$$\rho_{\scriptscriptstyle B} = \rho_{\scriptscriptstyle B1} + \tilde{\rho}_{\scriptscriptstyle B}$$

Here is

$$\frac{\partial \rho_{B1}}{\partial t} = -\dot{\chi}_{BA}\rho_{B_0} \implies \rho_{B1} = -\chi_{BA}\rho_{B_0} + C_B$$

From initial conditions at t = 0 we have

$$\rho_{B1}(0) = \rho_{B0}, \quad \chi_{BA}(0) = 0, \quad C_B = \rho_{B0}$$

Then

$$\rho_{B1} = (1 - \chi_{BA}) \rho_{B_0}$$





For $\tilde{
ho}_{\scriptscriptstyle R}$ we have

$$\frac{\partial \tilde{\rho}_{B}}{\partial t} + \frac{\partial}{\partial x} \left[(\rho_{B1} + \tilde{\rho}_{B}) \mathbf{v}_{B} \right] = 0$$

At the first approximation by neglecting of $\tilde{\mathcal{P}}_B$ in comparison with \mathcal{P}_{B1}

$$\frac{\partial \tilde{\rho}_{B}}{\partial t} = -\frac{\partial}{\partial x} \left[\rho_{B1} \mathbf{v}_{B} \right] = -\frac{\partial}{\partial x} \left[(1 - \chi_{BA}) \mathbf{v}_{B} \right] \rho_{B0}$$

If $\chi_{\rm BA}$ is not depending on x : $\dot{\tilde{\rho}}_{\rm B} = -\rho_{\rm B0}(1-\chi_{\rm BA})\dot{\varepsilon}_{\rm B}$

$$\tilde{\rho}_{B} = -\rho_{B0} \int_{0}^{t} (1 - \chi_{BA}) \dot{\varepsilon}_{B} d\tau = -\rho_{B0} \left[(1 - \chi_{BA}) \varepsilon_{B}(x, t) + \int_{0}^{t} \dot{\chi}_{BA} \varepsilon_{B} d\tau \right]$$





For $\rho_{\scriptscriptstyle B}$

$$\rho_{B} = \rho_{B0} \left[1 - \chi_{BA} - (1 - \chi_{BA}) \varepsilon_{B}(x, t) - \int_{0}^{t} \dot{\chi}_{BA} \varepsilon_{B} d\tau \right]$$

$$\sigma_{B} = \sigma_{B} \left[\chi_{BA} + (1 - \chi_{BA}) \varepsilon_{B}(x, t) + \int_{0}^{t} \dot{\chi}_{BA} \varepsilon_{B} d\tau \right]$$

Without of sources $\chi_{\mathit{BA}} = 0$ the equation of state is $\sigma_{\mathit{B}}(\mathcal{E}_{\mathit{B}})$

Let's note that the density $\,
ho_{_{\! B}}\,\,$ can turn into $\,0\,\,$ at moment $\,t^{^*}$

$$(1-\chi_{BA})(1-\varepsilon_B(x,t))-\int_0^{t^*}\dot{\chi}_{BA}\varepsilon_Bd\tau=0$$





For ρ_{A1}

$$\rho_{A1} = \chi_{AB}\rho_{A0} + C_A$$

$$\left. \rho_{A1} \right|_{t=0} = 0 \implies C_A = 0$$

$$\rho_{A1} = \chi_{AB} \rho_{A0}$$

$$\frac{\partial \tilde{\rho}_{A}}{\partial t} = -\frac{\partial}{\partial x} \left[\rho_{A1} \mathbf{v}_{A} \right] = -\frac{\partial}{\partial x} \left[\chi_{AB} \mathbf{v}_{A} \right] \rho_{A0} = -\rho_{A0} \dot{\varepsilon}_{A} \chi_{AB}$$

$$\rho_{A} = \rho_{A1} + \tilde{\rho}_{A} = \rho_{A0} \left[\chi_{AB} (1 - \varepsilon_{A}) + \int_{0}^{t} \dot{\chi}_{AB} \varepsilon_{A} d\tau \right]$$





Thus there are two equations for the determination of the densities of components $\,A\,$ and $\,B\,$ for given source $\,\chi_{{\scriptscriptstyle BA}}\,$

$$\frac{\rho_B}{\rho_{B0}} = (1 - \chi_{BA})(1 - \varepsilon_B(x, t)) - \int_0^t \dot{\chi}_{BA} \varepsilon_B d\tau$$

$$\frac{\rho_A}{\rho_{B0}} = \chi_{BA} (1 - \varepsilon_A(x, t)) + \int_0^t \dot{\chi}_{BA} \varepsilon_A d\tau$$

Equations of state for two components

$$\sigma_{B} = \sigma_{B} \left(\varepsilon_{B}(x,t) + \chi_{BA}(1 - \varepsilon_{B}(x,t)) + \int_{0}^{t} \dot{\chi}_{BA} \varepsilon_{B} d\tau \right)$$

$$\sigma_{a} = \sigma_{A} \left(\chi_{AB} \varepsilon_{A}(x,t) + 1 - \chi_{BA} - \int_{0}^{t} \dot{\chi}_{AB} \varepsilon_{A} d\tau \right)$$





or in case of linearization

$$\sigma_B \approx k_B \left[\varepsilon_B(x,t) + \chi_{BA} (1 - \varepsilon_B(x,t)) + \int_0^t \dot{\chi}_{BA} \varepsilon_B d\tau \right]$$

$$\sigma_a \approx k_A \left[\chi_{AB} \varepsilon_A(x,t) + 1 - \chi_{AB} - \int_0^t \dot{\chi}_{AB} \varepsilon_A d\tau \right]$$





Two main source terms

1.
$$\chi = \alpha \cdot (T - T_0)$$

$$\sigma = k_a (\varepsilon - \alpha \cdot (T - T_0))$$

$$\frac{\partial \tilde{\rho}_{A}}{\partial t} + \rho_{A_{0}} \cdot \dot{\varepsilon} = (\alpha T)^{\square} \rho_{A_{0}}$$

$$\tilde{\rho}_{A} = -\rho_{A_{0}} (\varepsilon - \alpha (T - T_{0}))$$

$$\sigma_{A} = k_{A} (1 - \frac{\rho_{A}}{\rho_{A_{0}}}) = k_{A} (\varepsilon - \alpha (T - T_{0}))$$





2.
$$\chi = \varepsilon \frac{n^+}{\kappa + n^+}$$

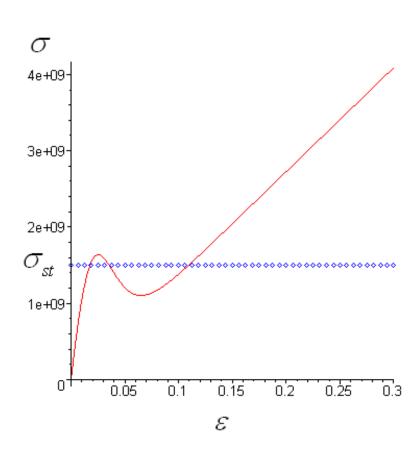
$$\tilde{\rho}_{A} = -\rho_{A_{0}}(\varepsilon - \varepsilon \frac{n^{+}}{\kappa + n^{+}}) = -\rho_{A_{0}}\varepsilon \frac{\kappa}{\kappa + n^{+}}$$

$$\sigma_{A} = E_{A} \varepsilon \frac{\kappa}{\kappa + n^{+}}$$





Static diagram







Two-component one-dimensional model of a thermo-elastic material of complex structure

Basic equations of one-dimensional model

$$\begin{cases} \frac{\partial \sigma_1}{\partial x} - \rho_1 \frac{\partial^2 u_1}{\partial t^2} + \rho_1 F_1^e - R = 0\\ \frac{\partial \sigma_2}{\partial x} - \rho_2 \frac{\partial^2 u_2}{\partial t^2} + \rho_2 F_2^e + R = 0 \end{cases}$$

$$\begin{cases} \lambda_{1} \frac{\partial^{2} T_{1}}{\partial x^{2}} - \rho_{1} c_{1} \frac{\partial T_{1}}{\partial t} = E_{1} \alpha_{1} \theta_{0} \frac{\partial^{2} u_{1}}{\partial x \partial t} - \rho_{1} b_{1} - \kappa \left(T_{1} - T_{2}\right) \\ \lambda_{2} \frac{\partial^{2} T_{2}}{\partial x^{2}} - \rho_{2} c_{2} \frac{\partial T_{2}}{\partial t} = E_{2} \alpha_{2} \theta_{0} \frac{\partial^{2} u_{2}}{\partial x \partial t} - \rho_{2} b_{2} + \kappa \left(T_{1} - T_{2}\right) \end{cases}$$





$$\sigma_{k} = E_{k} \left(\varepsilon_{k} - \alpha_{k} (\theta_{k} - \theta_{0}) \right)$$
 k=1,2

$$\begin{cases} E_1 \frac{\partial^2 u_1}{\partial x^2} - \rho_1 \frac{\partial^2 u_1}{\partial t^2} - E_1 \alpha_1 \frac{\partial T_1}{\partial x} + \rho_1 F_1^e - R = 0 \\ E_2 \frac{\partial^2 u_2}{\partial x^2} - \rho_2 \frac{\partial^2 u_2}{\partial t^2} - E_2 \alpha_2 \frac{\partial T_2}{\partial x} + \rho_2 F_2^e + R = 0 \end{cases}$$
Here
$$R = R_1 \left(u_1 - u_2 \right) + R_2 \left(\frac{\partial u_1}{\partial t} - \frac{\partial u_2}{\partial t} \right)$$

$$T_{_{k}}= heta_{_{k}}- heta_{_{0}}, \quad heta_{_{0}}$$
 - the reference temperature

 $m{R}$ - the force of intercomponental mechanical interaction

$$Q = \kappa (T_1 - T_2)$$
 – intercomponental temperature interactions.





On schedules T_2, V_2 are distinctly observed oscillations which frequency is equal to frequency of partial fluctuations of the second component on elastic bonds R_1 and it is approximately estimated as $f = \frac{1}{2\pi} \sqrt{\frac{R_1}{\rho_2}} \approx \frac{1}{2\pi} 0.741 \cdot 10^9 \approx 1.18 \cdot 10^8 \; Hz$

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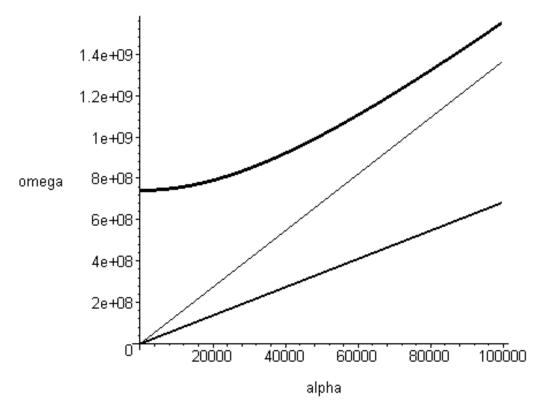


Fig. 6 Dispersive curves





Features of behaviour of two-component model under the action of non-stationary loadings

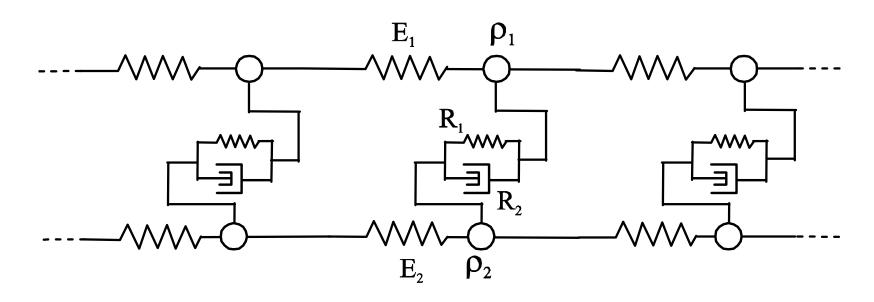


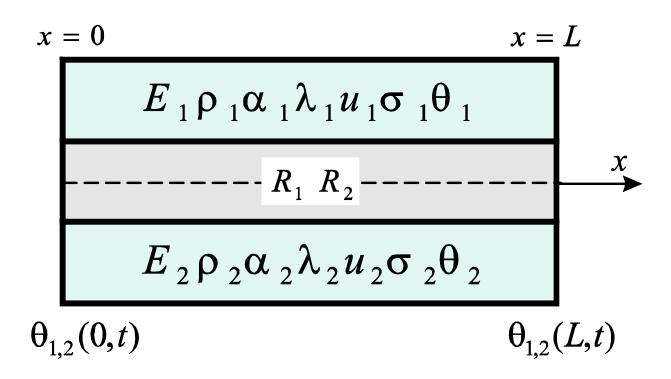
Fig. 3 The general view of the structural - rheological model

$$R = R_1 \Big(u_1 - u_2 \Big) + R_2 \Bigg(\frac{\partial u_1}{\partial t} - \frac{\partial u_2}{\partial t} \Bigg) \quad \text{- force interaction of the material components is supposed to be linear elastic-viscous.}$$





Model of deformable two-componental thermoelastic one-dimensional rod



Problem of statement of boundary conditions?





Pulse temperature loading of a semi-conductor crystal (a Si sample)

At very low temperatures ($\approx 4,2^0 \, K$) it is possible the generation of wave fluctuations of temperature

$$\lambda_1 \approx 0, \qquad \lambda_2 \neq 0$$

Density of silicon is

$$\rho \approx 2.33 \cdot 10^3 \, \frac{kg}{m^3}$$

The atom of silicon has 14 electrons.





The distribution of a wave thermo-mechanical pulse in a crystal semi-conductor Si sample.

Estimation of parameters of the two-component model

- Specific thermal capacity (at 20 – 100 0C) pprox 800~J/kg~K

$$c_1 \approx 0.001 \frac{J}{kg K}, \ c_2 \approx 1 \frac{J}{kg K}$$

- Heat conductivity (at 25°C)
$$\approx 84 \div 126 \frac{W}{m K}$$

$$\lambda_1 \approx 0 \frac{W}{m K}, \ \lambda_2 \neq 0 \frac{W}{m K}$$

- Temperature factor of linear expansion for silicon at normal temperature

$$\alpha \approx 2.33 \cdot 10^{-6} \ 1/K$$
 $E \approx 109 \cdot 10^{9} \ \frac{N}{m^{2}}$





Temperature factor of linear expansion for silicon at normal temperature $\alpha \approx 2.33 \cdot 10^{-6} \ 1/K$.

At temperature lower 120~K this factor becomes negative. For modelling (behind absence of more detailed information) it is accepted $\alpha_1 \approx 2.33 \cdot 10^{-9}~1/K, \ \alpha_2 \approx 2.33 \cdot 10^{-6}~1/K$

The elasticity module of silicon at normal temperature is $E \approx 109 \cdot 10^9 \frac{N}{m^2}$.

For two-component model it is accepted.

 $E_2 \neq 0$ means presence of own elasticity arising due to polarization of electric fields at displacement of electronic environments of atoms of silicon.





Density of silicon is $\rho \approx 2.33 \cdot 10^3 \, \frac{kg}{m^3}$. The atom of silicon has 14 electrons. They settle down on 3 environments: 2-8-4, on last environment are 4 electrons. Most likely, these last electrons "form" the second deformable component of considered two-component model. Probably, this statement will demand correction. Generally speaking, it is possible to think of formation of the second component by amount of electrons from 1 up to 14. Weight of a nucleus of atom of silicon is . Weight of electrons involved in formation of the second components is $9.11 \cdot 10^{-31} \div 1.275 \cdot 10^{-29} \, kg$.

According to it the densities of components of model could be accepted as

 $ho_1 pprox 2.33 \cdot 10^3 \, rac{kg}{m^3}$, $ho_2 pprox 0.0454 \div 0.635 \, rac{kg}{m^3}$. At the rate of 4 electrons, forming the second component we have the density of the component $ho_2 pprox 0.182 \, rac{kg}{m^3}$ Parameters of model accepted here to consideration have ratio among themselves, close to a reality.





Modules of elasticity and mass density define the next velocities of distribution of wave pulses on both components $v_2 \approx 13700 > v_1 \approx 6850$ $v_2 = 2v_1$.

Concerning factor of an intercomponental temperature exchange there are no data (reasons), most likely in conditions of the absence of free electrons for modelling it is necessary to accept factor κ close to zero $\kappa \approx 0 \frac{W}{m^3 \ K}$

At a choice of factor of intercomponental force interaction R_1 , probably, it is necessary to be guided $\rho_2 \approx 0.182 \, \frac{kg}{m^3}$ by value of the frequency $f \approx 1.18 \cdot 10^8 \, Hz$ of partial fluctuations of the second component respecting the first. If to accept and be guided by frequency for factor of elastic intercomponental interaction the estimation $R_1 \approx 1 \cdot 10^{17} \, \frac{N}{m^4}$ turns out. Concerning factor of force viscous interaction of the components R_2 while is not present precise reasons (assumptions), therefore we shall put $R_2 \approx 10^3 \, \frac{N \, s}{m^4}$





It is supposed, that the loading of an one-dimensional sample

 $0 < x < l \approx 5.5 \cdot 10^{-3} \ m$ at an end face x = 0 it is carried out by a short-term temperature pulse

$$T_1\big|_{x=0} = T_{10}\big(H(t) - H(t-\tau)\big), \frac{\partial T_2}{\partial x}\Big|_{x=0} = 0$$

$$T_2\big|_{x=0} = T_{20}\big(H(t) - H(t-\tau)\big), \frac{\partial T_1}{\partial x}\Big|_{x=0} = 0$$





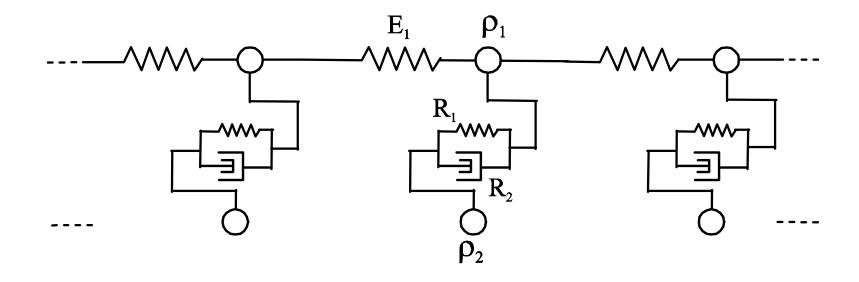


Fig.4 Structural - rheological circuit of one-dimensional two-component object with properties of non-metal





For modelling it is supposed to accept $\alpha_1 = 2.33 \cdot 10^{-9}, \alpha_2 = 2.33 \cdot 10^{-6}$

The temperature pulse $T_1|_{x=0} = T_{10} \left(H(t) - H(t-\tau) \right), \left. \frac{\partial T_2}{\partial x} \right|_{x=0} = 0$

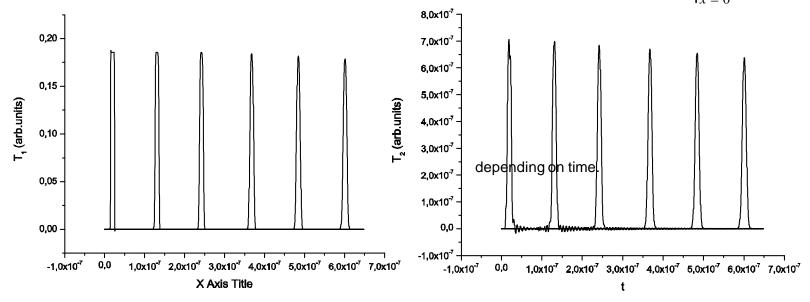


Fig. 4 Temperatures of the first and second components of sequence of sections $x \approx 0, x \approx 1, x \approx 2, x \approx 3, x \approx 4, x \approx 5 \,mm$





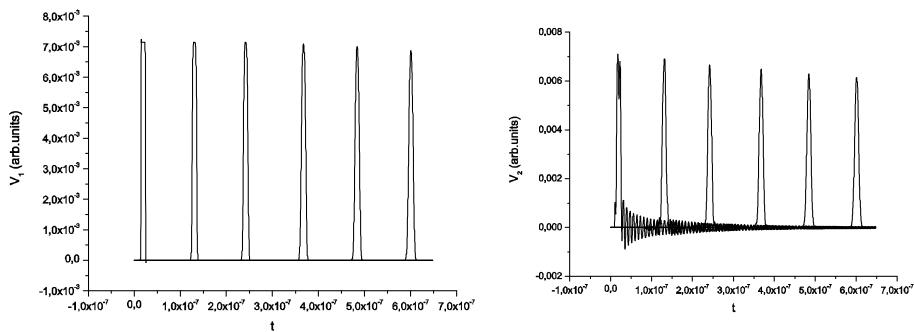


Fig. 5 Velocities of the first and second components of sequence of sections $x \approx 0$, $x \approx 1$, $x \approx 2$, $x \approx 3$, $x \approx 4$, $x \approx 5 mm$ depending on time.





On schedules T_2,V_2 are distinctly observed oscillations which frequency is equal to frequency of partial fluctuations of the second component on elastic bonds R_1 and it is approximately estimated as $f=\frac{1}{2\pi}\sqrt{\frac{R_1}{\rho_2}}\approx\frac{1}{2\pi}0.741\cdot 10^9\approx 1.18\cdot 10^8~Hz$

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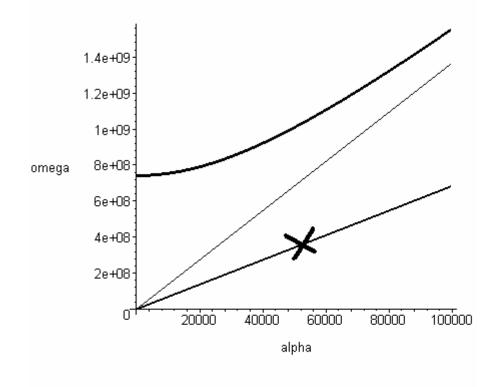


Fig. 6 Dispersive curves





The speed of distribution of a wave temperature pulse in the first component according to schedule Fig. of 4 is more as the value $v_1 = \sqrt{\frac{E_1}{\rho_1}}$. The reason consists that at adiabatic process of a heat transfer $\chi_1 \approx 0^-$, speed is approximately determined by expression that for the accepted values of parameters of model makes $\tilde{v}_1 \approx \sqrt{\frac{E_1}{\rho_1}} \sqrt{1 + \alpha_1 \frac{E_1 \alpha_1 \theta_0}{\rho_1 c_1}}$ $\tilde{v}_1 \approx 1.23 v_1$

In what kind the energy of laser excitation is transferred through a sample to measuring bolometer in section $x = l \approx 5 \, mm$

kinetic energy of the first component

$$K_1 = \frac{1}{2} \rho_1 V_1^2 \approx 0.57 \cdot 10^{-1}$$

- kinetic energy of the second component

$$K_2 = \frac{1}{2} \rho_2 V_2^2 \approx 0.33 \cdot 10^{-5}$$





thermal energy of the first component

$$E_{T1} = c_1 \rho_1 T_1 \approx 0.42$$

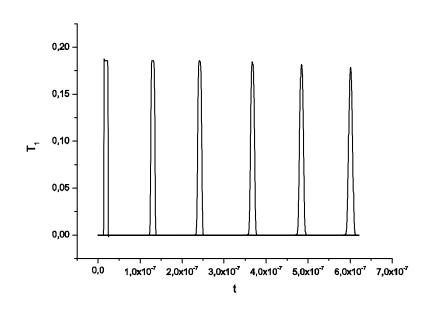
- thermal energy of the second component

$$E_{T2} = c_2 \rho_2 T_2 \approx 0.13 \cdot 10^{-6}$$

For the reduced size of force interaction of components

$$R_1 \approx 1 \cdot 10^{16}$$

instead of $R_1 \approx 1.10^{17}$



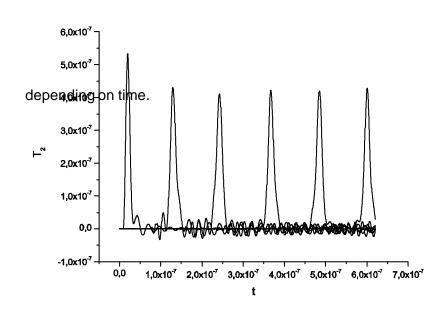
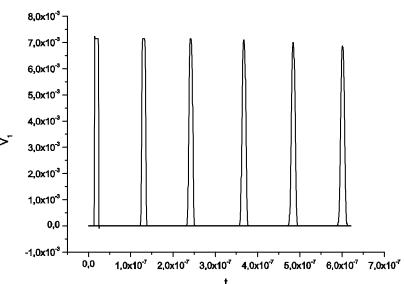


Fig. 7 Temperatures of the first and second components of sequence of sections $x \approx 0$, $x \approx 1$, $x \approx 2$, $x \approx 3$, $x \approx 4$, $x \approx 5$ mm





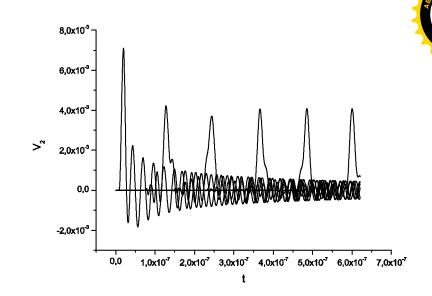
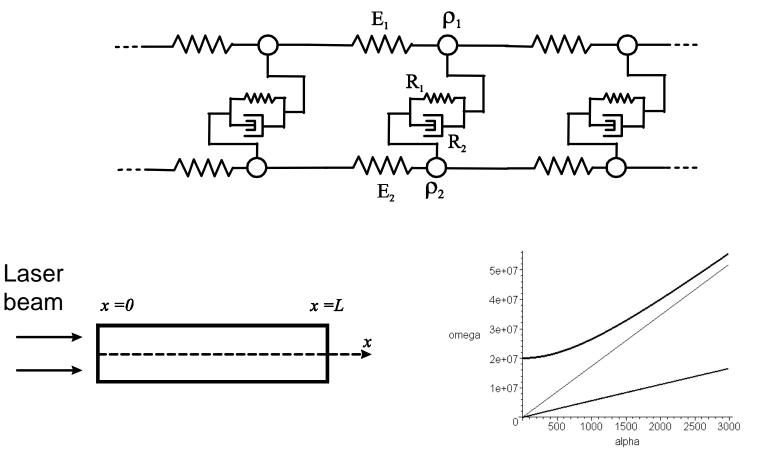


Fig. 8 Velocities of the first and second components of sequence of sections depending on time.





Use of the two-componental model of thermoelastic bodies for the analysis of propagation of wave pulses in a Si-sample, excited by short laser impact

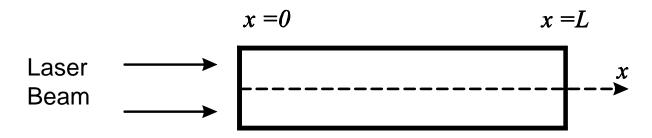


Dispersion curves

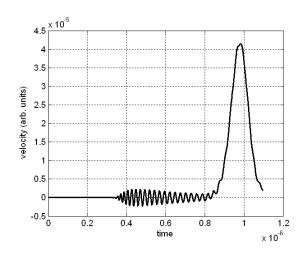




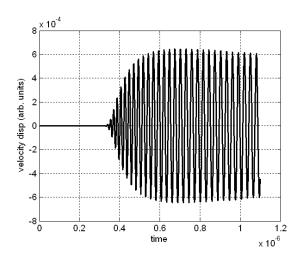
Use of the two-componental model of thermoelastic bodies for the analysis of propagation of wave pulses in a Si-sample, excited by short laser impact



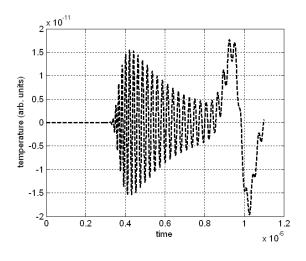
Temperature loading



Speed of end sections of a sample



Difference of speeds of components In end section



Temperature of end sections of a sample



Systems of thermoelasticity- heat and mass transfer-intercomponent exchange equations



$$\begin{cases} \frac{\partial \sigma_{1}}{\partial x} = \rho_{0} \frac{\partial^{2} u_{1}}{\partial t^{2}}, & \sigma_{1} = E_{0} \varepsilon_{1}^{(m)} \frac{1}{1 + n^{+} / \kappa}, \\ \varepsilon_{1}^{(m)} = \varepsilon_{1} - \alpha_{1} \left(T_{1} - T_{0}\right), & \varepsilon_{1} = \frac{\partial u_{1}}{\partial x}, \\ \frac{\partial n^{-}}{\partial t} = \frac{\partial}{\partial x} \left(D_{n} \left(T_{2}\right) \left(1 - b \varepsilon_{1}^{(m)}\right) \frac{\partial n^{-}}{\partial x}\right) + \frac{\partial}{\partial x} \left(D_{T} \left(n^{-}\right) \left(1 - b \varepsilon_{1}^{(m)}\right) \frac{\partial T_{2}}{\partial x}\right) - \\ - \alpha \left(\varepsilon_{1}, T_{1}\right) n^{-} + \beta \left(\varepsilon_{1}, T_{1}\right) n^{+}, \\ \frac{\partial n^{+}}{\partial t} = \alpha \left(\varepsilon_{1}, T_{1}\right) n^{-} - \beta \left(\varepsilon_{1}, T_{1}\right) n^{+}\right) - \frac{\partial}{\partial x} \left(n^{+} \frac{\partial u_{1}}{\partial t}\right), \\ c_{1} \rho_{0} \frac{\partial T_{1}}{\partial t} = \lambda_{1} \frac{\partial^{2} T_{1}}{\partial x^{2}} - E_{0} \frac{1}{1 + n^{+} / \kappa} \alpha_{1} T_{0} \frac{\partial \varepsilon_{1}}{\partial t} + \lambda_{0} \left(T_{1} - T_{2}\right), \\ c_{2} m_{2} n^{-} \frac{\partial T_{2}}{\partial t} = \lambda_{2} \frac{\partial^{2} T_{2}}{\partial x^{2}} + \lambda_{n} \frac{\partial}{\partial x} \left(D_{n} \left(T_{2}\right) \left(1 - b \varepsilon_{1}^{(m)}\right) \frac{\partial n^{-}}{\partial x}\right) - \lambda_{0} \left(T_{1} - T_{2}\right). \end{cases}$$



Numerical simulation



1



$$\sigma_{1}(0,t) = (1 - e^{-\lambda t}) \sigma_{0}, \quad \alpha = Const, \quad \beta = Const$$

$$u_{1}(x,0) = 0, \quad u_{1}(1,t) = 0, \quad T = const,$$

$$n^{-}(x,0) = C \begin{cases} 1, x \in \bigcup (a_{i},b_{i}), \\ 0, x \notin \bigcup (a_{i},b_{i}), \end{cases}$$

$$n^{+}(x,0) = 0,$$

$$\frac{\partial n^{-}}{\partial x}(0,t) = 0,$$

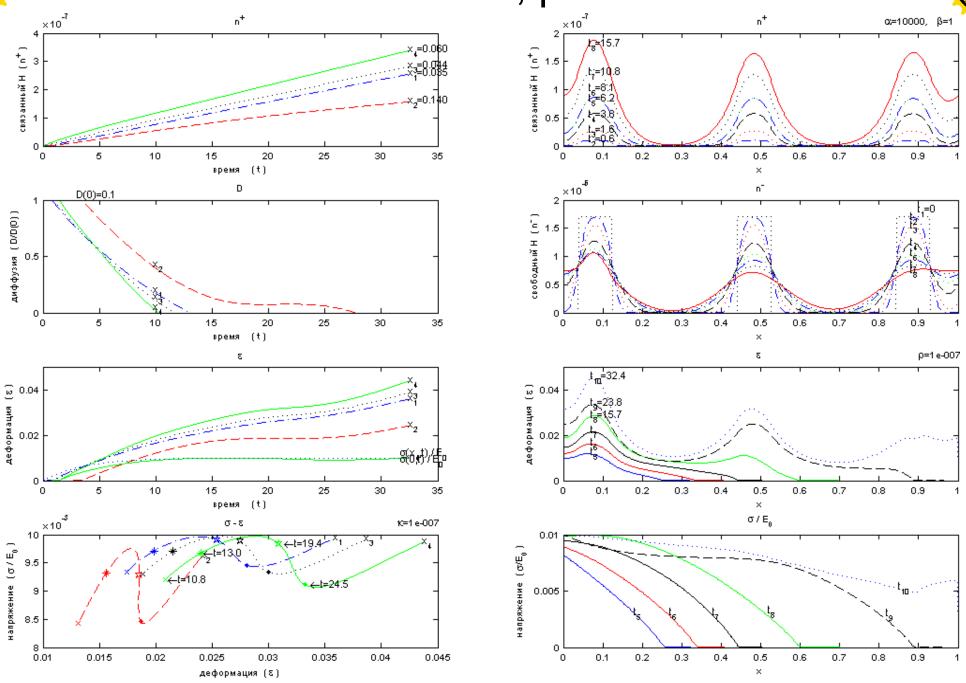
$$\frac{\partial n^{+}}{\partial x}(0,t) = 0,$$

$$\frac{\partial n^{+}}{\partial x}(1,t) = 0.$$

$$x_1 = 0.035, \ x_3 = 0.044, \ x_4 = 0.06, \ x_5 = 0.07, \ x_2 = 0.14$$



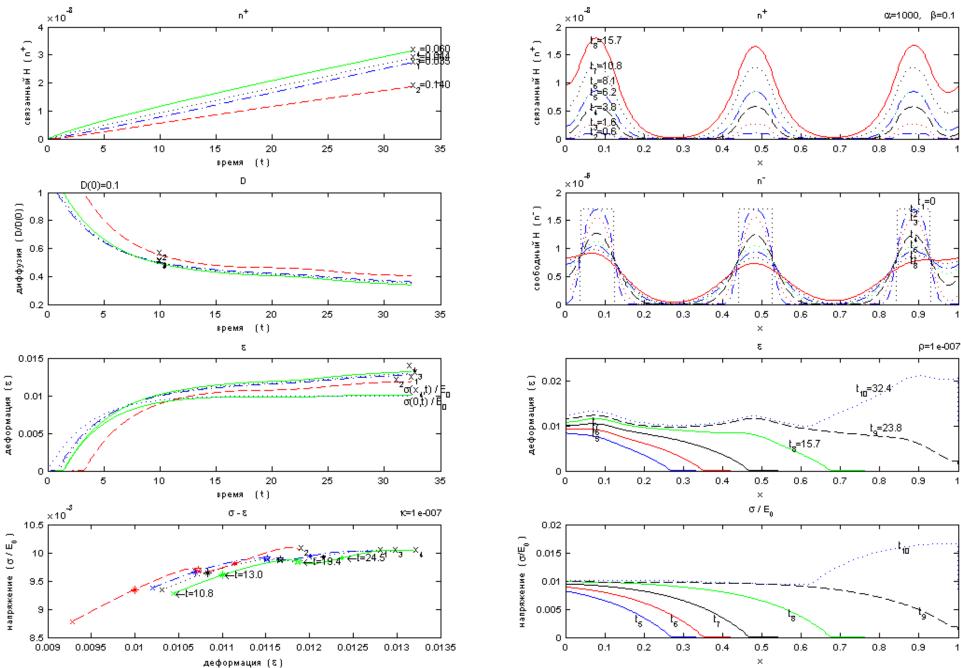
$\alpha = 10000, \beta = 1$





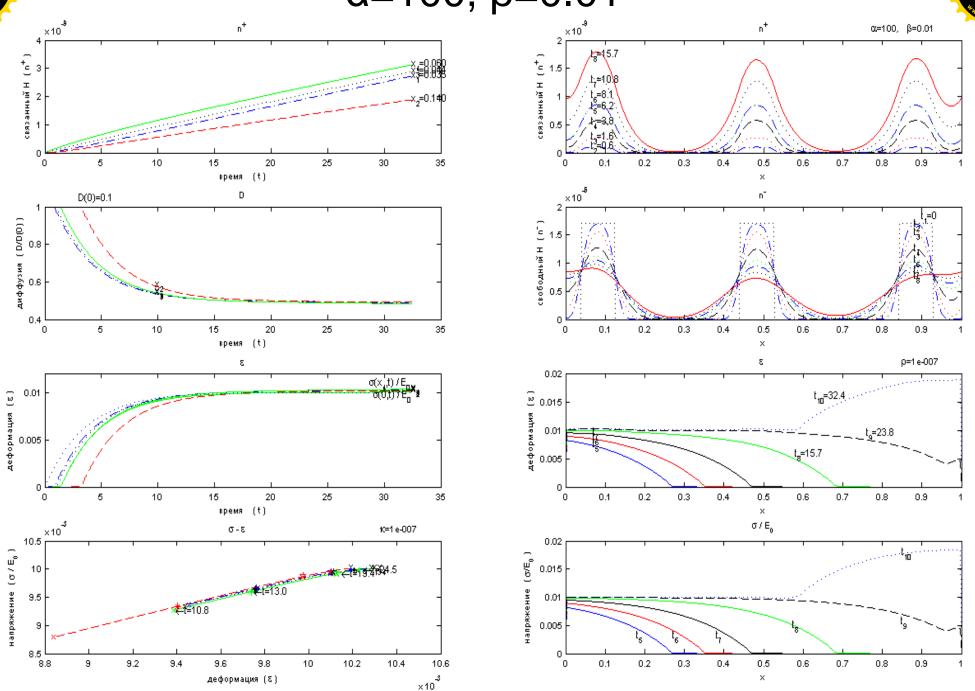
$\alpha = 1000, \beta = 0.1$







α =100, β =0.01







$$\sigma_1$$
 0 x 1

$$\sigma_1(0,t) = \delta(t),$$

$$u_1(x, 0) = 0$$
, $u_1(1, t) = 0$, $T = const$,

$$n^{-}(x,0) = C, n^{+}(x,0) = 0,$$

$$\frac{\partial n^{-}}{\partial x}(0,t) = 0, \frac{\partial n^{+}}{\partial x}(0,t) = 0,$$

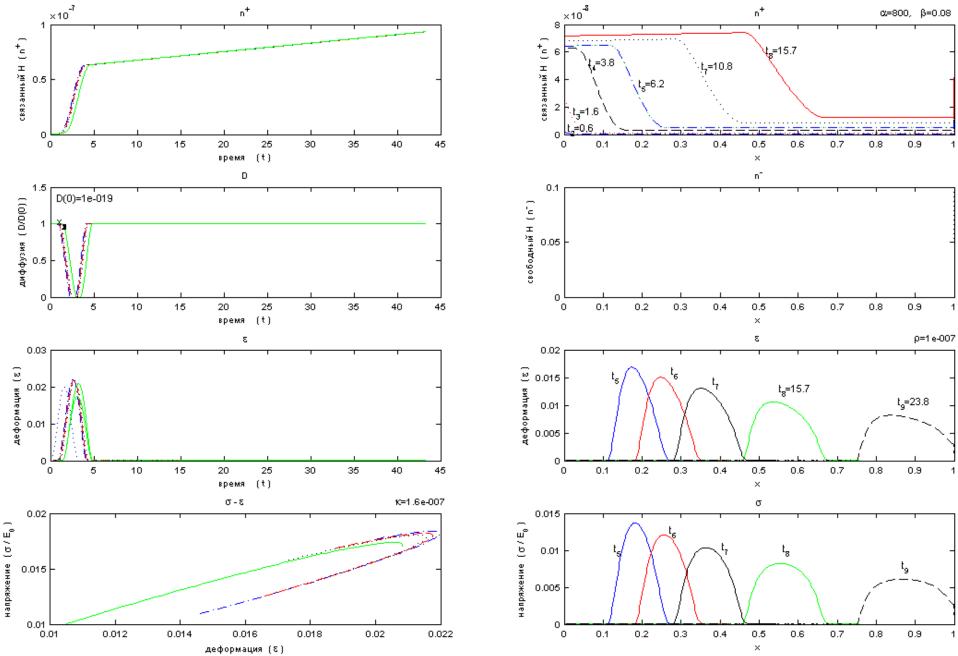
$$\frac{\partial n^{-}}{\partial x}(1,t) = 0, \frac{\partial n^{+}}{\partial x}(1,t) = 0.$$

$$x_1 = 0.035, \ x_2 = 0.04, \ x_3 = 0.044, \ x_4 = 0.06, \ x_5 = 0.07$$



$\alpha = 0.08 + 160 \cdot \epsilon, \beta = 0.08$









Improvement of material structure



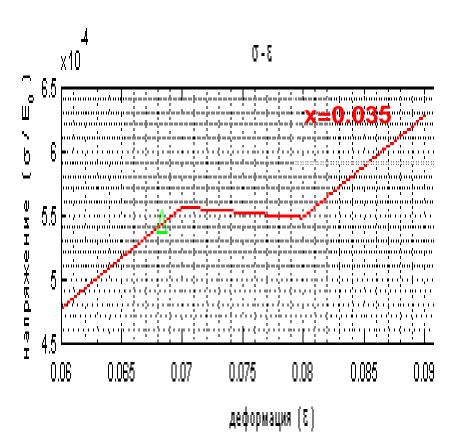
$$\sigma_1(0, t) = t \cdot a$$

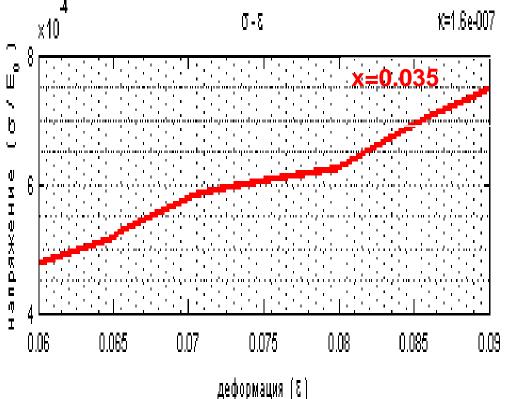
$$E_0 = E_0(\varepsilon),$$

$$\frac{\partial E_0}{\partial \varepsilon}(\varepsilon_1) = 0, \ \frac{\partial^2 E_0}{\partial \varepsilon^2}(\varepsilon_1) < 0$$

$$n^+(x,0) = n_0, \quad n^-(x,0) = 0$$

$$\alpha = 0$$
, $\beta = const \cdot \sqrt{\varepsilon - \varepsilon_1}$









Thank you for attention!